

Brief Introduction to Machine Learning

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- 1 Introduction
- 2 Binary Classification
- 3 Support Vector Machine
- 4 Nonlinear Support Vector Machine
- 5 Instance-based learning

What is Machine Learning?

Representation + Optimization + Evaluation

Pedro Domingos, A few useful things to know about machine learning,
Communications of the ACM, Vol. 55 Issue 10, 78-87, October 2012

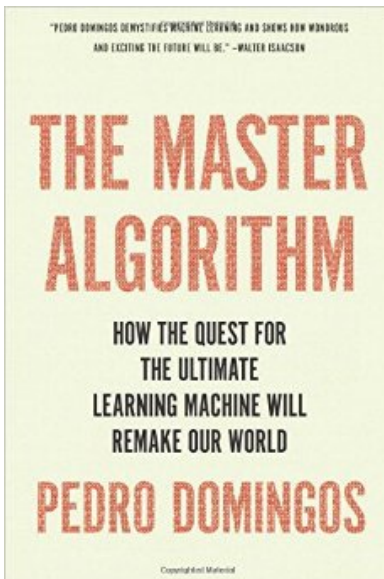
AlphaGo



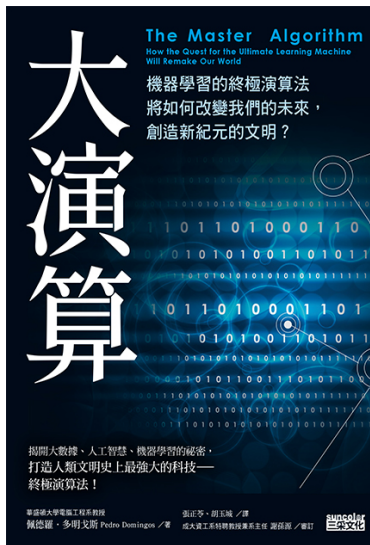
Mayhem Wins DARPA Cyber Grand Challenge



The Master Algorithm



The Master Algorithm



The Plan of My Lecture

- Only focus on *Supervised Learning*
- Will give you four basic algorithms
 - Online Perceptron Algorithm
 - Support Vector Machines
 - k-Nearest Neighbor
 - Naive Bayes Classifier
- Basic Concept of Learning Theorey
- Evaluation

Binary Classification Problem

(A Fundamental Problem in Data Mining)

- Find a decision function (classifier) to discriminate two categories data sets.
- Supervised learning in Machine Learning
 - Decision Tree, *Deep* Neural Network, k-NN and Support Vector Machines, etc.
- Discrimination Analysis in Statistics
 - Fisher Linear Discriminator
- Successful applications:
 - Marketing, Bioinformatics, Fraud detection

Binary Classification Problem

Given a training dataset

$$S = \{(x^i, y_i) | x^i \in \mathbb{R}^n, y_i \in \{-1, 1\}, i = 1, \dots, \ell\}$$

$$x^i \in A_+ \Leftrightarrow y_i = 1 \quad \& \quad x^i \in A_- \Leftrightarrow y_i = -1$$

Main Goal:

Predict the unseen class label for new data

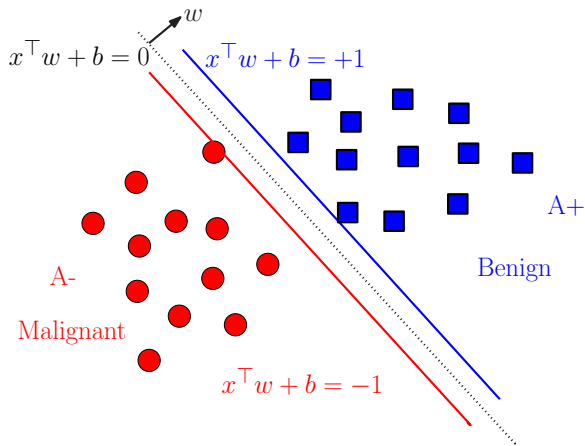
Find a function $f : \mathbb{R}^n \rightarrow \mathbb{R}$ by learning from data

$$f(x) \geq 0 \Rightarrow x \in A_+ \quad \text{and} \quad f(x) < 0 \Rightarrow x \in A_-$$

The simplest function is linear: $f(x) = w^\top x + b$

Binary Classification Problem

Linearly Separable Case



People of ACM: David Blei, (Sept. 9, 2014)



The recipient of the 2013 ACM- Infosys Foundation Award in the Computing Sciences, he is joining Columbia University this fall as a Professor of Statistics and Computer Science, and will become a member of Columbia's **Institute for Data Sciences and Engineering**.

What is the most important recent innovation in machine learning?

[A]: One of the main recent innovations in ML research has been that we (the ML community) can now scale up our algorithms to massive data, and I think that this has fueled the modern renaissance of ML ideas in industry. The main idea is called *stochastic optimization*, which is an adaptation of an *old algorithm invented by statisticians in the 1950s*.

What is the most important recent innovation in machine learning?

[A]: *In short, many machine learning problems can be boiled down to trying to find parameters that maximize (or minimize) a function.* A common way to do this is “gradient ascent,” iteratively following the steepest direction to climb a function to its top. This technique requires repeatedly calculating the steepest direction, and the problem is that this calculation can be expensive. *Stochastic optimization* lets us use *cheaper approximate calculations*. It has transformed modern machine learning.

Linear Learning Machines

- The simplest function is linear: $f(x) = w^T x + b$
- Finding this simplest function via an on-line and mistake-driven procedure
- Update the weight vector and bias when there is a misclassified point

Perceptron Algorithm (Primal Form)

Rosenblatt, 1956

- Given a training dataset S , and initial weight vector $w^0 = \mathbf{0}$ and the bias $b_0 = 0$

Repeat:

for $i = 1$ to ℓ

if $y_i(\langle w^k \cdot x^i \rangle + b_k) \leq 0$ then

$$w^{k+1} \leftarrow w^k + \eta y_i x^i$$

$$b_{k+1} \leftarrow b_k + \eta y_i R^2$$

$$k \leftarrow k + 1$$

end if

Until no mistakes made within the for loop

Return: $k, (w^k, b_k)$.

- What is k ?

$$R = \max_{1 \leq i \leq \ell} \|x^i\|$$

$$y_i(\langle w^{k+1} \cdot x^i \rangle + b_{k+1}) > y_i(\langle w^k \cdot x^i \rangle) + b_k ?$$

$$w^{k+1} \leftarrow w^k + \eta y_i x^i \text{ and } b_{k+1} \leftarrow b_k + \eta y_i R^2$$

$$\begin{aligned} y_i(\langle w^{k+1} \cdot x^i \rangle + b_{k+1}) &= y_i(\langle (w^k + \eta y_i x^i) \cdot x^i \rangle + b_k + \eta y_i R^2) \\ &= y_i(\langle w^k \cdot x^i \rangle + b_k) + y_i(\eta y_i (\langle x^i \cdot x^i \rangle + R^2)) \\ &= y_i(\langle w^k \cdot x^i \rangle + b_k) + \eta (\langle x^i \cdot x^i \rangle + R^2) \end{aligned}$$

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$$R = \max_{1 \leq i \leq \ell} \|x^i\|$$

Perceptron Algorithm Stop in Finite Steps

Theorem(Novikoff)

Let S be a non-trivial training set, and let

$$R = \max_{1 \leq i \leq \ell} \|x^i\|$$

Suppose that there exists a vector w_{opt} such that $\|w_{opt}\| = 1$ and

$$y_i(\langle w_{opt} \cdot x^i \rangle + b_{opt}) \geq \gamma \text{ for } 1 \leq i \leq \ell.$$

Then the number of mistakes made by the on-line perceptron algorithm on S is almost $(\frac{2R}{\gamma})^2$.

Perceptron Algorithm (Dual Form)

$$w = \sum_{i=1}^{\ell} \alpha_i y_i x^i$$

Given a linearly separable training set S and $\alpha = 0$, $\alpha \in \mathbb{R}^{\ell}$,
 $b = 0$, $R = \max_{1 \leq i \leq \ell} \|x_i\|$.

Repeat: for $i = 1$ to ℓ

 if $y_i (\sum_{j=1}^{\ell} \alpha_j y_j \langle x^j \cdot x^i \rangle + b) \leq 0$ then

$\alpha_i \leftarrow \alpha_i + 1$; $b \leftarrow b + y_i R^2$

 end if

end for

Until no mistakes made within the for loop return: (α, b)

What We Got in the Dual Form of Perceptron Algorithm?

- The number of updates equals: $\sum_{i=1}^{\ell} \alpha_i = \|\alpha\|_1 \leq \left(\frac{2R}{\gamma}\right)^2$
- $\alpha_i > 0$ implies that the training point (x_i, y_i) has been misclassified in the training process at least once.
- $\alpha_i = 0$ implies that removing the training point (x_i, y_i) will not affect the final results.
- The training data only appear in the algorithm through the entries of the Gram matrix, $G \in \mathbb{R}^{\ell \times \ell}$ which is defined below:

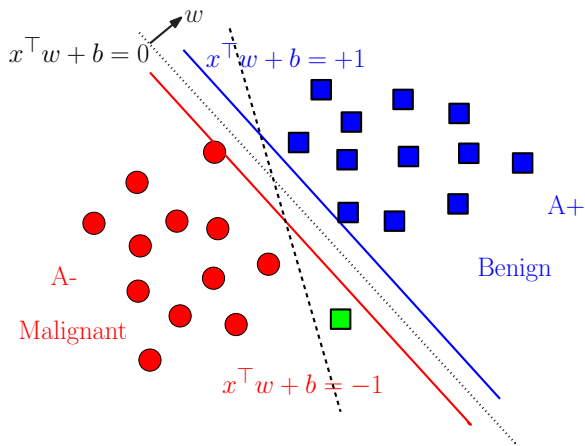
$$G_{ij} = \langle x_i, x_j \rangle$$

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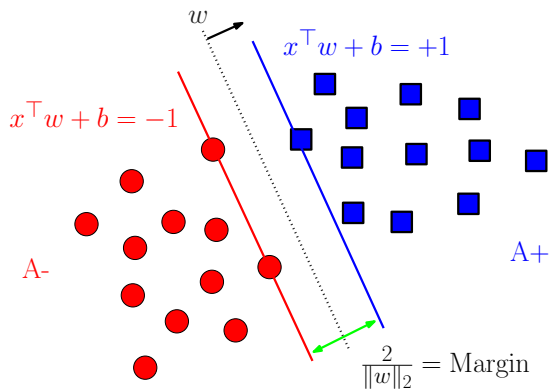
Binary Classification Problem

Linearly Separable Case



Support Vector Machines

Maximizing the Margin between Bounding Planes



Why Use Support Vector Machines?

Powerful tools for Data Mining

- SVM classifier is an optimally defined surface
- SVMs have a good geometric interpretation
- SVMs can be generated very efficiently
- Can be extended from linear to nonlinear case
 - Typically nonlinear in the input space
 - Linear in a higher dimensional "feature space"
 - Implicitly defined by a kernel function
- Have a sound theoretical foundation
 - Based on Statistical Learning Theory

Why We Maximize the Margin?

(Based on Statistical Learning Theory)

- The Structural Risk Minimization (SRM):
 - The expected risk will be less than or equal to empirical risk (training error)+ VC (error) bound
- $\|w\|_2 \propto VC \text{ bound}$
- $\min VC \text{ bound} \Leftrightarrow \min \frac{1}{2}\|w\|_2^2 \Leftrightarrow \max Margin$

Summary the Notations

Let $S = \{(x^1, y_1), (x^2, y_2), \dots, (x^\ell, y_\ell)\}$ be a training dataset and represented by matrices

$$A = \begin{bmatrix} (x^1)^\top \\ (x^2)^\top \\ \vdots \\ (x^\ell)^\top \end{bmatrix} \in \mathbb{R}^{\ell \times n}, D = \begin{bmatrix} y_1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & y_\ell \end{bmatrix} \in \mathbb{R}^{\ell \times \ell}$$

$A_i w + b \geq +1$, for $D_{ii} = +1$

$A_i w + b \leq -1$, for $D_{ii} = -1$, equivalent to $D(Aw + \mathbf{1}b) \geq \mathbf{1}$,

where $\mathbf{1} = [1, 1, \dots, 1]^\top \in \mathbb{R}^\ell$

Support Vector Classification (Linearly Separable Case, Primal)

The hyperplane (w, b) is determined by solving the minimization problem:

$$\min_{(w,b) \in \mathbb{R}^{n+1}} \frac{1}{2} \|w\|_2^2$$
$$D(Aw + \mathbf{1}b) \geq \mathbf{1},$$

It realizes the maximal margin hyperplane with geometric margin

$$\gamma = \frac{1}{\|w\|_2}$$

Support Vector Classification

(Linearly Separable Case, Dual Form)

The dual problem of previous MP:

$$\max_{\alpha \in \mathbb{R}^{\ell}} \mathbf{1}^{\top} \alpha - \frac{1}{2} \alpha^{\top} D A A^{\top} D \alpha$$

subject to

$$\mathbf{1}^{\top} D \alpha = 0, \alpha \geq \mathbf{0}$$

Applying the KKT optimality conditions, we have $w = A^{\top} D \alpha$. But where is b ?

Don't forget

$$\mathbf{0} \leq \alpha \perp D(Aw + \mathbf{1}b) - \mathbf{1} \geq \mathbf{0}$$

Dual Representation of SVM

(Key of Kernel Methods: $w = A^T D \alpha^* = \sum_{i=1}^{\ell} y_i \alpha_i^* A_i^T$)

The hypothesis is determined by (α^*, b^*)

$$\begin{aligned} h(x) &= \text{sgn}(\langle x \cdot A^T D \alpha^* \rangle + b^*) \\ &= \text{sgn}\left(\sum_{i=1}^{\ell} y_i \alpha_i^* \langle x^i \cdot x \rangle + b^*\right) \\ &= \text{sgn}\left(\sum_{\alpha_i^* > 0} y_i \alpha_i^* \langle x^i \cdot x \rangle + b^*\right) \end{aligned}$$

Remember : $A_i^T = x_i$

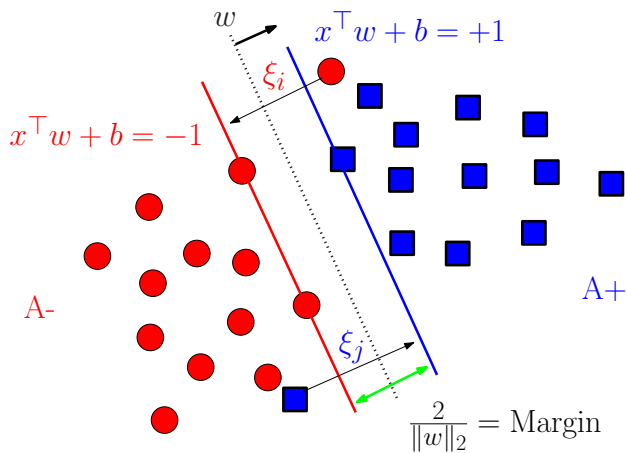
Soft Margin SVM (Nonseparable Case)

- If data are not linearly separable
 - Primal problem is infeasible
 - Dual problem is unbounded above
- Introduce the slack variable for each training point

$$y_i(w^\top x^i + b) \geq 1 - \xi_i, \quad \xi_i \geq 0, \quad \forall i$$

- The inequality system is always feasible e.g.

$$w = \mathbf{0}, \quad b = 0, \quad \xi = \mathbf{1}$$



Robust Linear Programming

Preliminary Approach to SVM

$$\begin{aligned}
 \min_{w, b, \xi} \quad & \mathbf{1}^\top \xi \\
 \text{s.t.} \quad & D(Aw + \mathbf{1}b) + \xi \geq \mathbf{1} \quad (LP) \\
 & \xi \geq \mathbf{0}
 \end{aligned}$$

where ξ is nonnegative slack(*error*) vector

- The term $\mathbf{1}^\top \xi$, 1-norm measure of *error* vector, is called the *training error*
- For the linearly separable case, at solution of(LP): $\xi = \mathbf{0}$

Support Vector Machine Formulations

(Two Different Measures of Training Error)

2-Norm Soft Margin:

$$\min_{(w, b, \xi) \in \mathbb{R}^{n+1+\ell}} \frac{1}{2} \|w\|_2^2 + \frac{C}{2} \|\xi\|_2^2$$

$$D(Aw + \mathbf{1}b) + \xi \geq \mathbf{1}$$

1-Norm Soft Margin (Conventional SVM)

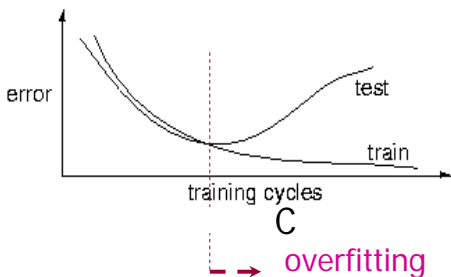
$$\min_{(w, b, \xi) \in \mathbb{R}^{n+1+\ell}} \frac{1}{2} \|w\|_2^2 + C \mathbf{1}^\top \xi$$

$$D(Aw + \mathbf{1}b) + \xi \geq \mathbf{1}$$

$$\xi \geq \mathbf{0}$$

Tuning Procedure

How to determine C ?



The final value of parameter is one with the maximum testing set correctness!

1-Norm SVM

(Different Measure of Margin)

1-Norm SVM:

$$\min_{(w, b, \xi) \in \mathbb{R}^{n+1+\ell}} \quad \|w\|_1 + C\mathbf{1}^\top \xi$$

$$D(Aw + \mathbf{1}b) + \xi \geq \mathbf{1}$$

$$\xi \geq \mathbf{0}$$

Equivalent to:

$$\min_{(s, w, b, \xi) \in \mathbb{R}^{2n+1+\ell}} \quad \mathbf{1}s + C\mathbf{1}^\top \xi$$

$$D(Aw + \mathbf{1}b) + \xi \geq \mathbf{1}$$

$$-s \leq w \leq s$$

$$\xi \geq \mathbf{0}$$

Good for feature selection and similar to the LASSO

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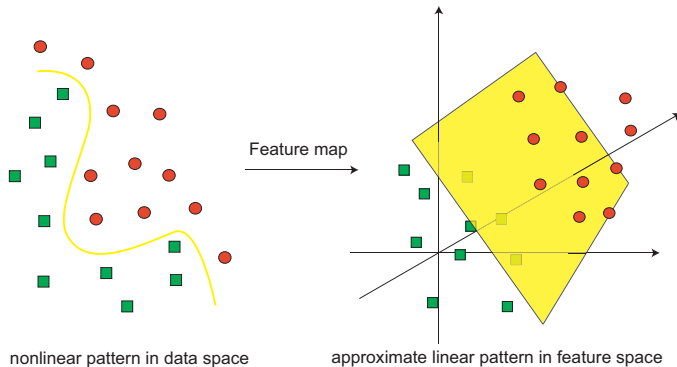
Two-spiral Dataset (94 white Dots & 94 Red Dots)



Learning in Feature Space (Could Simplify the Classification Task)

- Learning in a high dimensional space could degrade generalization performance
 - This phenomenon is called *curse of dimensionality*
- By using a *kernel function*, that represents the inner product of training example in feature space, we never need to explicitly know the nonlinear map
 - Even do not know the dimensionality of feature space
- There is no free lunch
 - Deal with a huge and dense kernel matrix
 - Reduced kernel can avoid this difficulty

$$X \xrightarrow{\Phi} F$$



Linear Machine in Feature Space

Let $\phi : X \rightarrow F$ be a nonlinear map from the input space to some feature space

The classifier will be in the form(*primal*):

$$f(x) = \left(\sum_{j=1}^? w_j \phi_j(x) \right) + b$$

Make it in the *dual* form:

$$f(x) = \left(\sum_{i=1}^{\ell} \alpha_i y_i \langle \phi(x^i) \cdot \phi(x) \rangle \right) + b$$

Kernel: Represent Inner Product in Feature Space

Definition: A kernel is a function $K : X \times X \rightarrow \mathbb{R}$
such that *for all* $x, z \in X$

$$K(x, z) = \langle \phi(x) \cdot \phi(z) \rangle$$

where $\phi : X \rightarrow F$

The classifier will become:

$$f(x) = \left(\sum_{i=1}^{\ell} \alpha_i y_i K(x^i, x) \right) + b$$

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Instance-based Learning

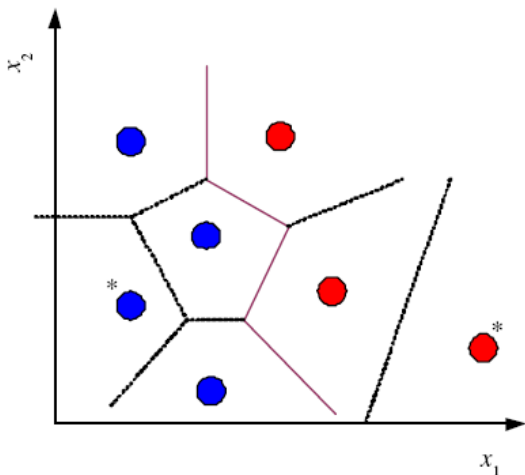
- Fundamental philosophy: Two instances that are *close to each other* or *similar to each other* they should share with the **same label**
- Also known as *memory-based learning* since what they do is store the training instances in a lookup table and *interpolate* from these.
- It requires memory of $\mathcal{O}(N)$
- Given an input similar ones should be found and finding them requires computation of $\mathcal{O}(N)$
- Such methods are also called *lazy learning* algorithms. Because they do NOT compute a model when they are given a training set but postpone the computation of the model until they are given a new test instance (query point)

k-Nearest Neighbors Classifier

- Given a query point x^o , we find the k training points $x^{(i)}$, $i = 1, 2, \dots, k$ *closest* in *distance* to x^o
- Then classify using *majority vote* among these k neighbors.
- Choose k as an odd number will avoid the tie. Ties are broken at random
- If all attributes (features) are real-valued, we can use Euclidean distance. That is $d(x, x^o) = \|x - x^o\|_2$
- If the attribute values are *discrete*, we can use *Hamming distance*, which counts the number of *nonmatching* attributes

$$d(x, x^o) = \sum_{j=1}^n \mathbf{1}(x_j \neq x_j^o)$$

1-Nearest Neighbor Decision Boundary (Voronoi)



Distance Measure

- Using different distance measurements will give very different results in k -NN algorithm.
- Be careful when you compute the distance
- We might need to *normalize* the scale between different attributes. For example, yearly income vs. daily spend
- Typically we first standardize each of the attributes to have mean zero and variance 1

$$\hat{x}_j = \frac{x_j - \mu_j}{\sigma_j}$$



Learning Distance Measure

- Finding a distance function $d(x^i, x^j)$ such that if x^i and x^j are belong to the *class* the distance is *small* and if they are belong to the *different classes* the distance is large.
- Euclidean distance: $\|x^i - x^j\|_2^2 = (x^i - x^j)^\top (x^i - x^j)$
- Mahalanobis distance: $d(x^i, x^j) = (x^i - x^j)^\top M (x^i - x^j)$ where M is a positive semi-definited matrix.

$$\begin{aligned} (x^i - x^j)^\top M (x^i - x^j) &= (x^i - x^j)^\top L^\top L (x^i - x^j) \\ &= (Lx^i - Lx^j)^\top (Lx^i - Lx^j) \end{aligned}$$

- The matrix L can be with the size $k \times n$ and $k \ll n$

Reference

-  C. J. C Burges. "A Tutorial on Support Vector Machines for Pattern Recognition", Data Mining and Knowledge Discovery, Vol. 2, No. 2, (1998) 121-167.
-  N. Cristianini and J. Shawe-Taylor. "An Introduction to Support Vector Machines", Cambridge University Press,(2000).